

On Matrix Representations of Octonions

Hassan. S. Ali *

Department of Mathematics, Faculty of Education, University of Benghazi, Ghemines, Libya.

Received date: 20-9-2021 Accepted date: 10 / 12 / 2021

المخلص:

الأعداد الرباعية الحقيقية $\mathbb{H}$ على $\mathbb{R}$ جبر قسمة تنسقي هي قابلة للتمثيل بمصفوفات رباعية حقيقية. الأعداد الثمانية الحقيقية $\mathbb{O}$ على $\mathbb{R}$ جبر قسمة غير تنسقي وبذلك لا يمكن تمثيلها خطياً بمصفوفات حقيقية كما في حالة $\mathbb{H}$. النقطة الأساسية في هذا البحث هي تمثيل الأعداد الثمانية بزوج مرتب من المصفوفات الرباعية الحقيقية.

الكلمات المفتاحية:

الأعداد الرباعية، الأعداد الثمانية، جبر قسمة غير تنسقي، مصفوفات حقيقية، التمثيل الخطي.

Abstract

The real Quaternions $\mathbb{H}$ over $\mathbb{R}$ is an associative division algebra. They can be linearly represented by 4×4 real matrices. The real Octonions $\mathbb{O}$ over $\mathbb{R}$ is a non-associative division algebra. They can't be represented linearly by matrices as in the case of $\mathbb{H}$. The point of this paper is to represent Octonions linearly by ordered pairs of two 4×4 matrices.

Keywords: hypercomplex; quaternions; octonions; associative; alternative and division algebras

1. INTRODUCTION

Hypercomplex numbers of importance are of dimensions 1, 2, 4 and 8. They are respectively the reals $\mathbb{R}$, the complex numbers $\mathbb{C}$, the quaternions (Hamiltonians) $\mathbb{H}$, and the Octonions (Cayley numbers) $\mathbb{O}$. The basis of $\mathbb{H}$ is $\{1, i, j, k\}$ where $i^2 = j^2 = k^2 = ijk = -1$. For $q = a + bi + cj + dk$ in $\mathbb{H}$, the conjugate and norm of q are respectively defined by $q^* = a - bi - cj - dk$ and $\|q\|_{\mathbb{H}} = q^*q = a^2 + b^2 + c^2 + d^2$. Thus we have

Lemma 1.

$$(i) q^{**} = q \quad (ii) qq^* = q^*q \quad (iii) (q_1 q_2)^* = q_2^* q_1^* \\ (iv) \|rq\|_{\mathbb{H}} = |r| \|q\|_{\mathbb{H}} \quad (v) \|q_1 q_2\|_{\mathbb{H}} = \|q_1\|_{\mathbb{H}} \|q_2\|_{\mathbb{H}}.$$

$\mathbb{R}, \mathbb{C}$, and $\mathbb{H}$ are associative algebras over $\mathbb{R}$. Therefore they can be represented linearly by matrices as follows [1].

$$\mathbb{R}: r \mapsto [r]$$

$$\mathbb{C}: a + bi \mapsto \begin{bmatrix} a & -b \\ b & a \end{bmatrix}$$

$$\mathbb{H}: a + bi + cj + dk \mapsto \begin{bmatrix} a & -b & -c & -d \\ b & a & d & -c \\ c & -d & a & b \\ d & c & -b & a \end{bmatrix}$$

Also, $\mathbb{H}$ can be represented by 2×2 -complex matrices as follows:

$$z + wj \mapsto \begin{bmatrix} z & -w^* \\ w & z^* \end{bmatrix}$$

$\mathbb{O}$ is a non-associative algebra over $\mathbb{R}$ (see theorem 7). Therefore $\mathbb{O}$ cannot be linearly represented by the same way above. However, there are different approaches to this problem. They produce different results [2, 3]. The point of this paper is to represent octonions linearly by ordered pairs of two matrices.

2. CONSTRUCTION

We use the Cayley-Dikson theorem [4] to construct hypercomplex numbers.

Let Γ be the set of all hypercomplex numbers of dimension n ($n=1, 2$, or 4). The next set of hypercomplex numbers Γ' of dimension $2n$ is constructed as follows

$$\Gamma' = \{(\alpha, \beta): \alpha, \beta \in \Gamma\}$$

Addition and scalar multiplication on Γ' are defined by

$$(\alpha, \beta) + (\gamma, \delta) = (\alpha + \gamma, \beta + \delta), \text{ and}$$

$$r(\alpha, \beta) = (r\alpha, r\beta) \text{ where } r \in \mathbb{R}$$

Theorem 2. Γ' is a vector space over $\mathbb{R}$ of dimension $2n$

Proof.

Γ is a vector space over $\mathbb{R}$ of dimension n .

Let $u_1, u_2, \dots, u_n$ be the basis of Γ .

Γ' is a vector space with respect to the addition and scalar multiplication just defined. The basis of Γ' is $(u_1, 0), (u_2, 0), \dots, (u_n, 0), (0, u_1), (0, u_2), \dots, (0, u_n)$. Therefore the dimension of Γ' is $2n$.

Corollary 3: $\Gamma' \cong \Gamma \oplus \Gamma$ as vector space.

We introduced the conjugate and multiplication on Γ' in terms of conjugate and multiplication of Γ as follows:

$$(\alpha, \beta)^* = (\alpha^*, -\beta) \text{ and}$$

*Correspondence:

Hassan. S. Ali

Hassansamor1972@gmail.com

$$(\alpha, \beta)(\gamma, \delta) = (\alpha\gamma - \delta^*\beta, \delta\alpha + \beta\gamma^*).$$

Lemma 4 . (i) $\phi^{**} = \phi$ (ii) $(\phi\psi)^* = \psi^*\phi^*$, for any $\phi, \psi \in \Gamma'$

Proof .

Let

$\phi, \psi \in \Gamma'$. Then $\phi = (\alpha, \beta)$,
 $\psi = (\gamma, \delta)$ where $\alpha, \beta, \gamma, \delta \in \Gamma$

$$(i) \phi^* = (\alpha, \beta)^* = (\alpha^*, -\beta)$$

$$\phi^{**} = (\alpha^*, -\beta)^* = (\alpha^{**}, \beta) = (\alpha, \beta) = \phi$$

$$(ii) (\phi\psi) = (\alpha, \beta)(\gamma, \delta) = (\alpha\gamma - \delta^*\beta, \delta\alpha + \beta\gamma^*)$$

$$(\phi\psi)^* = (\alpha\gamma - \delta^*\beta, \delta\alpha + \beta\gamma^*)^*$$

$$= (\gamma^*\alpha^* - \beta^*\delta, -\beta\gamma^* - \delta\alpha) = (\gamma^*, -\delta)(\alpha^*, -\beta) = \psi^*\phi^*$$

The norm of a hyper complex number θ is defined by

$$\|\theta\|_{\Gamma'} = \theta^*\theta.$$

$$\text{Lemma 5 . } \|\phi\psi\|_{\Gamma'} = \|\phi\|_{\Gamma'}\|\psi\|_{\Gamma'}$$

Proof .

$$\begin{aligned} \|\phi\psi\|_{\Gamma'} &= (\phi\psi)^*(\phi\psi) = (\psi^*\phi^*)(\phi\psi) = \psi^*(\phi^*\phi)\psi \\ &= \psi^*\|\phi\|_{\Gamma'}\psi = \|\phi\|_{\Gamma'}\psi^*\psi = \|\phi\|_{\Gamma'}\|\psi\|_{\Gamma'} \end{aligned}$$

$$\text{Lemma 6 . } \|(\alpha, \beta)\|_{\Gamma'} = \|\alpha\|_{\Gamma} + \|\beta\|_{\Gamma}$$

Proof .

$$\begin{aligned} \|(\alpha, \beta)\|_{\Gamma'} &= (\alpha, \beta)^*(\alpha, \beta) = (\alpha^*, -\beta)(\alpha, \beta) \\ &= (\alpha^*\alpha + \beta^*\beta, \beta\alpha^* - \beta\alpha^*) \\ &= (\alpha^*\alpha + \beta^*\beta, 0) = \|\alpha\|_{\Gamma} + \|\beta\|_{\Gamma} \end{aligned}$$

Octonions $\mathbb{O}$

$$\mathbb{O} = \{(q_1, q_2) : q_1, q_2 \in \mathbb{H}\}, \text{ and } \|(q_1, q_2)\|_{\mathbb{O}} = \|q_1\|_{\mathbb{H}} + \|q_2\|_{\mathbb{H}}.$$

Theorem 7. $\mathbb{O}$ is a non-commutative, a non-associative and alternative division algebra over $\mathbb{R}$ of dimension 8.

Proof .

$$\text{Let } (i, j), (k, i) \in \mathbb{O}$$

$$(i, j)(k, i) = (ik + ij, -1 - jk) = (-j + k, -1 - i)$$

$$(k, i)(i, j) = (ki + ji, jk + 1) = (j - k, i + 1)$$

Then $\mathbb{O}$ is a non-commutative.

$$\text{Let } (i, j), (k, i), (j, k) \in \mathbb{O}$$

$$((i, j)(k, i))(j, k) = (-j + k, -1 - i)(j, k) = (1 - i - k + j, i - 1 + j + k)$$

$$(i, j)((k, i)(j, k)) = (i, j)(-i + j, -1 - k) = (1 + k + j + i, -i - j - k + 1)$$

Then $\mathbb{O}$ is non-associative.

$$\text{Let } \phi = (q_1, q_2), \psi = (q_3, q_4) \in \mathbb{O}$$

$$(\phi\psi)\psi = ((q_1, q_2)(q_3, q_4))(q_3, q_4) =$$

$$(q_1q_3 - q_4^*q_2, q_4q_1 + q_2q_3^*)(q_3, q_4)$$

$$=$$

$$((q_1q_3)q_3 - (q_4^*q_2)q_3 - q_4^*(q_4q_1) - q_4^*(q_2q_3^*), q_4(q_1q_3) - q_4(q_4^*q_2) + (q_4q_1)q_3^* + (q_2q_3^*)q_3^*)$$

$$=$$

$$(q_1(q_3q_3) - (q_4^*q_4)q_1 - q_4^*(q_2q_3) - q_4^*(q_2q_3^*), (q_4q_1)q_3 + (q_4q_1)q_3^* - (q_4q_4^*)q_2 + q_2(q_3^*q_3^*))$$

$$=$$

$$(q_1(q_3q_3) - q_1(q_4^*q_4) - (q_4^*q_2)q_3 - (q_4^*q_2)q_3^*, q_4q_1(q_3 + q_3^*) - q_2(q_4q_4^*) + q_2(q_3^*q_3^*))$$

$$= (q_1(q_3q_3 - q_4^*q_4) - q_4^*q_2(q_3 + q_3^*), q_4q_1(q_3 + q_3^*) + q_2(q_3^*q_3^* - q_4q_4^*))$$

$$= (q_1(q_3q_3 - q_4^*q_4) - (q_3 + q_3^*)q_4^*q_2, q_4(q_3 + q_3^*)q_1 + q_2(q_3^*q_3^* - q_4q_4^*))$$

$$= (q_1(q_3q_3 - q_4^*q_4) - (q_4q_3^* + q_4q_3)^*q_2, (q_4q_3 + q_4q_3^*)q_1 + q_2(q_3q_3 - q_4^*q_4)^*) = (q_1, q_2)(q_3q_3 - q_4^*q_4, q_4q_3 + q_4q_3^*) = \phi(\psi\psi)$$

$$(\phi\phi)\psi = ((q_1, q_2)(q_1, q_2))(q_3, q_4) = (q_1q_1 - q_2^*q_2, q_2q_1 + q_2q_1^*)(q_3, q_4)$$

$$=$$

$$((q_1q_1)q_3 - (q_2^*q_2)q_3 - q_4^*(q_2q_1) - q_4^*(q_2q_1^*), q_4(q_1q_1) - q_4(q_2^*q_2) + (q_2q_1)q_3^* + (q_2q_1^*)q_3^*)$$

$$= ((q_1q_1)q_3 - q_4^*q_2(q_1 + q_1^*) - (q_2^*q_2)q_3, q_4(q_1q_1) + q_2(q_1 + q_1^*)q_3^* - q_4(q_2^*q_2))$$

$$= ((q_1q_1)q_3 - (q_1 + q_1^*)q_4^*q_2 - (q_2^*q_2)q_3, (q_4q_1)q_1 + q_2q_3^*(q_1 + q_1^*) - q_4(q_2q_2^*))$$

$$=$$

$$(q_1(q_1q_3) - q_1(q_4^*q_2) + q_1^*(q_4^*q_2) - q_3(q_2^*q_2), (q_4q_1)q_1 + (q_2q_3^*)q_1 + q_2(q_3^*q_1^*) - q_2(q_2^*q_4))$$

$$= (q_1(q_1q_3 - q_4^*q_2) - (q_4q_1 + q_2q_3^*)^*q_2, (q_4q_1 + q_2q_3^*)q_1 + q_2(q_1q_3 - q_4^*q_2)^*)$$

$$= (q_1, q_2)(q_1q_3 - q_4^*q_2, q_4q_1 + q_2q_3^*)$$

$$= (q_1, q_2)((q_1, q_2)(q_3, q_4)) = \phi(\phi\psi)$$

Then $\mathbb{O}$ is alternative algebra.

$$\text{Let } (q_1, q_2) \neq 0 \text{ in } \mathbb{O}$$

$$\text{Then } (q_1, q_2)^{-1} = \frac{(q_1, q_2)^*}{\|(q_1, q_2)\|_{\mathbb{O}}} = \frac{(q_1^*, -q_2)}{\|q_1\|_{\mathbb{H}} + \|q_2\|_{\mathbb{H}}}$$

Thus $\mathbb{O}$ is division algebra over $\mathbb{R}$.

3. LINEAR REPRESENTATIONS

Let $\mu_g: \mathbb{H} \rightarrow M_4(\mathbb{R})$ be the algebra monomorphism of the matrix representation of $\mathbb{H}$.

$$\text{Then } \mu_{\mathbb{H}}(a + bi + cj + dk) = \begin{bmatrix} a & -b & -c & -d \\ b & a & d & -c \\ c & -d & a & b \\ d & c & -b & a \end{bmatrix}$$

Define $\mu_{\mathbb{O}}: \mathbb{O} \rightarrow M_4(\mathbb{R}) \oplus M_4(\mathbb{R})$ be given by

$$\mu_{\mathbb{O}}(q_1, q_2) = (\mu_{\mathbb{H}}(q_1), \mu_{\mathbb{H}}(q_2)).$$

Theorem 8 . $\mu_{\mathbb{O}}$ is an algebra monomorphism.

Proof .

Let $(q_1, q_2), (q_3, q_4) \in \mathbb{O}$ and $a \in \mathbb{R}$.

$$\mu_{\mathbb{O}}(a(q_1, q_2)) = \mu_{\mathbb{O}}(aq_1, aq_2) = (\mu_{\mathbb{H}}(aq_1), \mu_{\mathbb{H}}(aq_2))$$

$= (a \mu_{\mathbb{H}}(q_1), a \mu_{\mathbb{H}}(q_2))$ since $\mu_{\mathbb{H}}$ monomorphism

$$= a (\mu_{\mathbb{H}}(q_1), \mu_{\mathbb{H}}(q_2)) = a \mu_{\mathbb{O}}((q_1, q_2)).$$

$$\mu_{\mathbb{O}}((q_1, q_2) + (q_3, q_4)) = \mu_{\mathbb{O}}(q_1 + q_3, q_2 + q_4)$$

$$= (\mu_{\mathbb{H}}(q_1 + q_3), \mu_{\mathbb{H}}(q_2 + q_4))$$

$= (\mu_{\mathbb{H}}(q_1) + \mu_{\mathbb{H}}(q_3), \mu_{\mathbb{H}}(q_2) + \mu_{\mathbb{H}}(q_4))$ since $\mu_{\mathbb{H}}$ monomorphism

$$= (\mu_{\mathbb{H}}(q_1), \mu_{\mathbb{H}}(q_2)) + (\mu_{\mathbb{H}}(q_3), \mu_{\mathbb{H}}(q_4)) = \mu_{\mathbb{O}}(q_1, q_2) + \mu_{\mathbb{O}}(q_3, q_4)$$

$$\mu_{\mathbb{O}}((q_1, q_2)(q_3, q_4)) = \mu_{\mathbb{O}}(q_1 q_3 - q_4^* q_2, q_4 q_1 + q_2 q_3^*)$$

$$= (\mu_{\mathbb{H}}(q_1 q_3 - q_4^* q_2), \mu_{\mathbb{H}}(q_4 q_1 + q_2 q_3^*))$$

$$= (\mu_{\mathbb{H}}(q_1) \mu_{\mathbb{H}}(q_3) - \mu_{\mathbb{H}}(q_4^*) \mu_{\mathbb{H}}(q_2), \mu_{\mathbb{H}}(q_4) \mu_{\mathbb{H}}(q_1) + \mu_{\mathbb{H}}(q_2) \mu_{\mathbb{H}}(q_3^*))$$

since $\mu_{\mathbb{H}}$ monomorphism and $\mu_{\mathbb{H}}(q_4^*) = (\mu_{\mathbb{H}}(q_4))^*$,

$$\mu_{\mathbb{H}}(q_3^*) = (\mu_{\mathbb{H}}(q_3))^*$$

$$= (\mu_{\mathbb{H}}(q_1), \mu_{\mathbb{H}}(q_2)) (\mu_{\mathbb{H}}(q_3), \mu_{\mathbb{H}}(q_4))$$

$$= \mu_{\mathbb{O}}(q_1, q_2) \mu_{\mathbb{O}}(q_3, q_4)$$

Therefore $\mu_{\mathbb{O}}$ is homomorphism .

Suppose that $\mu_{\mathbb{O}}(q_1, q_2) = (0, 0)$.

Then $(\mu_{\mathbb{H}}(q_1), \mu_{\mathbb{H}}(q_2)) = (0, 0)$ and

$\mu_{\mathbb{H}}(q_1) = 0, \mu_{\mathbb{H}}(q_2) = 0$. Then $q_1 = 0, q_2 = 0$ since $\mu_{\mathbb{H}}$ monomorphism

Therefore $\mu_{\mathbb{O}}$ is an algebra monomorphism.

Corollary 9. $\mu_{\mathbb{O}}(\mathbb{O})$ is a subalgebra of $M_4(\mathbb{R}) \oplus M_4(\mathbb{R})$ of dimension 8 with basis

$(1, 0), (i, 0), (j, 0), (k, 0), (0, 1), (0, i), (0, j), (0, k)$.

Let $\phi \in \mathbb{O}$. Then $\phi = (q_1, q_2); q_1, q_2 \in \mathbb{H}$.

$$\mu_{\mathbb{O}}: \mathbb{O} \rightarrow (\mu_{\mathbb{H}}(q_1), \mu_{\mathbb{H}}(q_2))$$

Let $\mu'_{\mathbb{O}}: \mathbb{O} \rightarrow M_4(\mathbb{R}) \oplus M_4(\mathbb{R})$ be give by

$$\mu'_{\mathbb{O}}(\phi) = \begin{bmatrix} \mu_{\mathbb{H}}(q_1) & 0 \\ 0 & \mu_{\mathbb{H}}(q_2) \end{bmatrix}$$

Theorem 10 . $\mu'_{\mathbb{O}}$ is an algebra monomorphism

Proof .

Let $\phi = (q_1, q_2), \psi = (q_3, q_4) \in \mathbb{O}$ and $a \in \mathbb{R}$

$$\mu'_{\mathbb{O}}(a\phi) = \mu'_{\mathbb{O}}(aq_1, aq_2) = \begin{bmatrix} \mu_{\mathbb{H}}(aq_1) & 0 \\ 0 & \mu_{\mathbb{H}}(aq_2) \end{bmatrix}$$

$$= \begin{bmatrix} a\mu_{\mathbb{H}}(q_1) & 0 \\ 0 & a\mu_{\mathbb{H}}(q_2) \end{bmatrix} = a \begin{bmatrix} \mu_{\mathbb{H}}(q_1) & 0 \\ 0 & \mu_{\mathbb{H}}(q_2) \end{bmatrix} = a \mu'_{\mathbb{O}}(\phi).$$

$$\mu'_{\mathbb{O}}(\phi + \psi) = \mu'_{\mathbb{O}}(q_1 + q_3, q_2 + q_4) = \begin{bmatrix} \mu_{\mathbb{H}}(q_1 + q_3) & 0 \\ 0 & \mu_{\mathbb{H}}(q_2 + q_4) \end{bmatrix}$$

$$= \begin{bmatrix} \mu_{\mathbb{H}}(q_1) + \mu_{\mathbb{H}}(q_3) & 0 \\ 0 & \mu_{\mathbb{H}}(q_2) + \mu_{\mathbb{H}}(q_4) \end{bmatrix}$$

$$= \begin{bmatrix} \mu_{\mathbb{H}}(q_1) & 0 \\ 0 & \mu_{\mathbb{H}}(q_2) \end{bmatrix} + \begin{bmatrix} \mu_{\mathbb{H}}(q_3) & 0 \\ 0 & \mu_{\mathbb{H}}(q_4) \end{bmatrix}$$

$$= \mu'_{\mathbb{O}}(\phi) + \mu'_{\mathbb{O}}(\psi).$$

$$\mu'_{\mathbb{O}}(\phi\psi) = \mu'_{\mathbb{O}}((q_1, q_2)(q_3, q_4)) = \mu'_{\mathbb{O}}(q_1 q_3 - q_4^* q_2, q_4 q_1 + q_2 q_3^*)$$

$$= \begin{bmatrix} \mu_{\mathbb{H}}(q_1 q_3 - q_4^* q_2) & 0 \\ 0 & \mu_{\mathbb{H}}(q_4 q_1 + q_2 q_3^*) \end{bmatrix} =$$

$$\begin{bmatrix} \mu_{\mathbb{H}}(q_1) \mu_{\mathbb{H}}(q_3) - \mu_{\mathbb{H}}(q_4^*) \mu_{\mathbb{H}}(q_2) & 0 \\ 0 & \mu_{\mathbb{H}}(q_4) \mu_{\mathbb{H}}(q_1) + \mu_{\mathbb{H}}(q_2) \mu_{\mathbb{H}}(q_3^*) \end{bmatrix}$$

$$= (\mu_{\mathbb{H}}(q_1), \mu_{\mathbb{H}}(q_2)) (\mu_{\mathbb{H}}(q_3), \mu_{\mathbb{H}}(q_4)) = \mu'_{\mathbb{O}}(\phi) \mu'_{\mathbb{O}}(\psi).$$

Then $\mu'_{\mathbb{O}}$ is homomorphism.

Suppose that $\mu'_{\mathbb{O}}(\phi) = \mu'_{\mathbb{O}}(q_1, q_2) = 0$

$$\text{Then } \begin{bmatrix} \mu_{\mathbb{H}}(q_1) & 0 \\ 0 & \mu_{\mathbb{H}}(q_2) \end{bmatrix} = \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix}$$

And $\mu_{\mathbb{H}}(q_1) = 0, \mu_{\mathbb{H}}(q_2) = 0$. Therefore $q_1 = 0, q_2 = 0$

Then $\mu_{\mathbb{O}}'$ is an algebra monomorphism.

Our main result is therefore given as follows.

Corollary 11. The matrix representation of Octonions is given by

$(q_1, q_2) \mapsto \begin{bmatrix} \mu_{\mathbb{H}}(q_1) & 0 \\ 0 & \mu_{\mathbb{H}}(q_2) \end{bmatrix}$, a diagonal block matrix.

4. CONCLUSIONS

The real Octonions have been represented linearly by order pairs of two real 4×4 matrices.

Our method maybe extended to represent the real sedenions by order pairs of two real 8×8 matrices.

5. ACKNOWLEDGMENTS

The author wishes to express the utmost gratitude to Prof. Kahtan H. Alzubaidy for suggesting the problem and for his numerous useful comments during the preparation of this paper.

6. REFERENCES

1. Jacobson N. Basic algebra 1 (2nd edition). New York: W.H. Freeman; 1996.
2. Körtesi P. Modeling hypercomplex numbers. Acta Electrotechnica et Informatica. 2012, Jul 1,12(3): 38-41
3. Tian Y. Matrix representations of octonions and their applications. Advances in applied Clifford Algebras 2000, 10 (1): 61-90
4. Baez J. The Cayles-Dickson construction, in the octonions. Bulletin of the American Mathematical Society. 2002, 39:145-205.